MA2 series





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Product Segments

Industrial Motion

TecHome's MA2 series linear actuator was specifically designed for applications which face harsh working environments and require ruggedness and durability. Its IP69K protection ensures it will withstand high temperature, high pressure water jets, and the ingress of dust and other solid contaminants. The MA2 also has optional Reed switches along the outer tube which allow users to adjust the stroke length. For improved control and accuracy of motion, the MA2 can be customized with many different feedback options depending on your application requirements. Example applications suitable for the MA2: Agricultural equipment such as spreaders, harvesters, grain handlers, combines and tractors. Example applications suitable for the MA2:

Agricultural equipment such as spreaders, harvesters, grain handlers, combines and tractors. Commercial and industrial applications such as commercial lawn mowers, scrubbers and sweepers, material handling equipment and livestock ventilation systems.

General Features

- Voltage of motor Maximum load Maximum speed at full load: Stroke Minimum installation dimension IP rating Certificate Operational temperature range at full performance Options
- 12V DC, 24V DC, 36V DC; 6,000N in push and pull 43mm/s (1000 N) 25~1000mm Stroke + 131mm Up to IP69K EN 61000-6-1, EN 61000-6-3 +5°C~+45°C

Hall sensor(s), POT

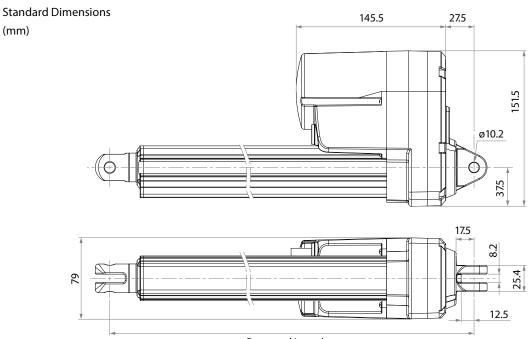
MOTION AND AUTOMATION

P: 07 3297 9797 A: 33 Perrin Drive, Underwood, QLD, 4119, Australia E: info@techome.com.au W: www.techome.com.au

MA2 series

Drawing

(mm)



Retracted Length

Load and Speed

CODE	Load (N)		Self Locking	Typical Current (A)		Typical Speed (mm/s)	
	Push	Pull	Force (N)	No Load 24V DC	With Load 24V DC	No Load 24V DC	With Load 24V DC
Motor Spee	ed (5200RPM, d	uty cycle 25%)					
F	1000	1000	1300	2.7	8.4	52.5	43.0
G	2000	2000	2600	2.4	7.5	25.5	22.3
н	4000	4000	5200	2.3	8.0	13.2	11.1
J	6000	6000	7800	2.0	6.8	6.6	6.1

Note

1 With a 12V motor, the current is approximately twice the current measured in 24V. With a 36V motor, the current is approximately two-thirds the current measured in 24V; speed will be similar for both voltages.

2 This self-locking force level is reached only when a short circuit is applied on the terminals of the motor. All the TiMOTION control boxes have this feature built-in.

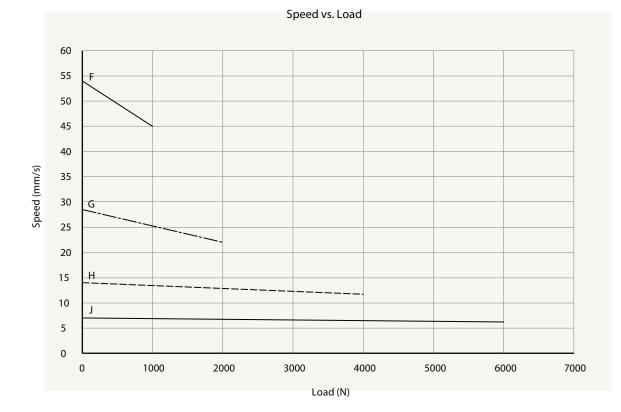
3 Standard stroke: Min. ≥25mm, Max. please refer to below table.

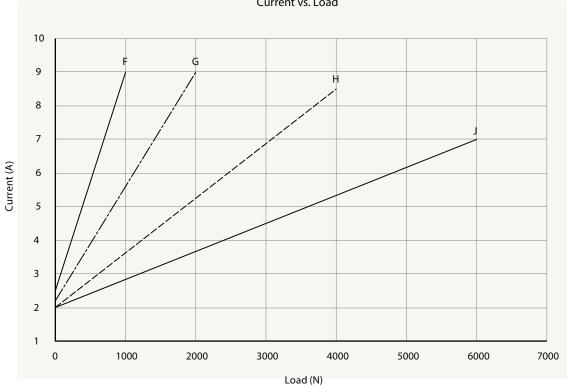
Load (N)	Max Stroke (mm)
≥ 4000	600
= 8000	800
= 10000	1000



Performance Data (24V DC Motor)

Motor Speed (5200RPM)





Current vs. Load

Note

1 The performance data in the curve charts shows theoretical value.



MA2 Ordering Key

MA2

T.

2 = 24V DC 5 = 24V DC, thermal contrõl= 36V DC, thermal control Load and Speed See page 2 Stroke (mm) Retracted Length (mm) Retracted Length (mm) See page 5 Rear Attachment (mm) 1 = Aluminum casting, clevis U, slot 8.2, depth 12.5, hole 10.2 See page 6 3 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 10.2 See page 6 3 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 12.8 4 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 12.2 Front Attachment (mm) 2 =Iron inner tube with punched hole, without slot, hole 10.2 2 =Iron inner tube with punched hole, without slot, hole 10.2 2 =lron inner tube with punched hole, without slot, hole 12.8 4 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 10.2 5 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 12.8 4 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 12.8 4 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 12.2 5 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 12.2 6 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 12.2 6 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 12.8 K =Rod end bearing, hole 12.8 Direction of 1 = 90° 2 = 0° Rear Attachmen					
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$6 = \text{Aluminum casting, clevis U, slot} 8.2, \text{ depth 15.0, hole 12.8}$ $K = \text{Rod end bearing, hole 12.8}$ Direction of Rear Attachment (Counterclockwise) $1 = 90^{\circ} \qquad 2 = 0^{\circ}$ Functions for $1 = \text{Two switches at full retracted/extended positions to cut current}$ $2 = \text{Two switches at full retracted/extended positions to cut current} + \text{third one in be}$					
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6 = Two switches at full retracted/extended positions to cut current + condicional	 1 = Two switches at full retracted/extended positions to cut current 2 = Two switches at full retracted/extended positions to cut current + third one in between to sen 				
0 – Two switches at full reflacted / extended positions to cut current + send signal					
Reed Sensor on the 0 = Without 1 = One Reed sensor 2 = Two Reed sensors Outer Ttube					
Output Signals0 = Without1 = POT4 = Hall sensor*15 = Hall	all sensor*2				
Connector 2 = Tinned leads					
See page 7					
	raight, 2000				
P Rating 1 = Without 3 = IP66 8 = IP69K					
$2 = IP54 \qquad 6 = IP66D$					
Manual Drive 0 = Without 1 = With					



Retracted Length (mm)

1. Calculate A+B+C+D = Y

2. Retracted length needs to \geq Stroke + Y

A. Rear/ Front	Attachment					
Front	Rear Attachment					
Attachment	1	2,3,4				
1, 3	+131	+134				
2, 4, 5, 6	+161	+164				
К	+178	+181				
C. Output Sigr	nal					
CODE						
0, 4, 5, 6, 7	-					
1	+20					

B. Load V.S. Stroke				
Stroke (mm)	Load (N)			
25~150	-			
151~200	-			
201~250	+10			
251~300	+20			
301~350	+30			
351~400	+40			
401~450	+50			
451~500	+60			
501~550	+70			
551~600	+80			
601~650	+90			
651~700	+100			
701~750	+110			
751~800	+120			
801~850	+130			
851~900	+140			
901~950	+155			
951~1000	+160			



MA2 Ordering Key Appendix

Rear Attachment (mm)

8.2, depth 12.5, hole 10.2



8.2, depth 15.0, hole 10.2

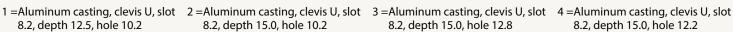
20.5

ø10.2

25.4

8.2

15



20.5

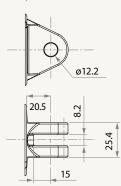
ø12.8

25.4

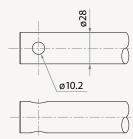
8.2

15

8.2, depth 15.0, hole 12.2

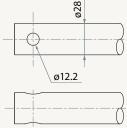


- Front Attachment (mm)
- 1 = Iron inner tube with punched hole, without slot, hole 10.2

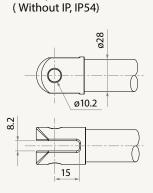


hole, without slot, hole 12.2

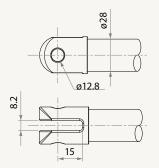
3 = Iron inner tube with punched



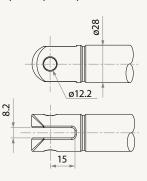
4 = Aluminum casting, clevis U, slot 5 = Aluminum casting, clevis U, slot 5 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 10.2

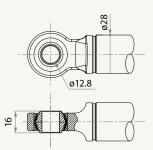


6 = Aluminum casting, clevis U, slot K = Rod end bearing, hole 12.8 8.2, depth 15.0, hole 12.8 (Without IP, IP54)

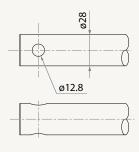


8.2, depth 15.0, hole 12.2 (IP66D, IP69K)





3 = Iron inner tube with punched hole, without slot, hole 12.8



8.2, depth 15.0, hole 12.2

ø28

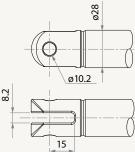
ø12.2

15

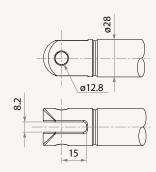
(Without IP, IP54)

8.2

4 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 10.2 (IP66D, IP69K)



6 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 12.8 (IP66D, IP69K)

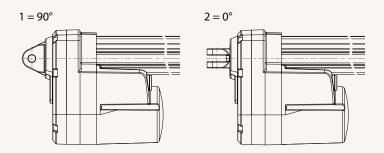




6

MA2 Ordering Key Appendix

Direction of Rear Attachment (Counterclockwise)



Functions for Limit Switches

Wire Definitions						
CODE	(Green)	(Red)	(White)	(Black)	(Yellow)	(Blue)
1	extend (VDC+)	N/A	N/A	N/A	retract (VDC+)	N/A
2	extend (VDC+)	N/A	middle switch pin B	middle switch pin A	retract (VDC+)	N/A
6	extend (VDC+)	N/A	upper limit switch	lower limit switch	retract (VDC+)	N/A

Connector

2 = Tinned leads

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